

In the Specification:

Please replace the original specification in its entirety with the substitute specification submitted herewith.

In the Claims:

 Cancel Claims 4, 20 and 21, without prejudice.

Please rewrite the following claims in amended form:

Sub B17
1. (Amended) A system for controlling a load-lifting apparatus (1), having a controllable drive (2), having a load-bearing element (5) which is connected to the drive (2) and is aligned in a vertical path (Z-Z) as a result of gravitational force at least in a rest position, having a load-receiving device (7) which is connected to the load-bearing element (5), and having a regulating circuit for load-balancing purposes, characterized in that the regulating circuit for load-balancing purposes comprises a device (11) for generating a path-dependent signal (S), which contains information corresponding to a substantially vertical (Z-Z) movement of the load-bearing element (5) and serves as an input signal for controlling the drive (2) to balance a load in the vertical path.

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2. (Amended) The system as claimed in claim 1, characterized in that the drive (2) is an electric motor and has the device (11) for generating the path-dependent signal (S).

3. (Amended) The system as claimed in claim 1, characterized in that the drive (2) is a fluidically acting drive device.

Sub B17
4. (Amended) The system as claimed in Claim 1, characterized in that the load-bearing element (5) comprises a load-bearing parallelogram in which four sub-arms are connected to one another at joints with a horizontal pivot axis and in which the angle position